Joshua Zhanson

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Employment -

Microsoft

Data & Applied Scientist 2 | Microsoft Designer

Mountain View, CA October 2022 - Present

- Template retrieval system: Led improvement of template retrieval search using a joint transformer + TF-IDF + LLM architecture, increasing precision by 93% and recall by 115%. Evaluated using offline crowdlabeling and online A/B flighting.
- Diffusion design search: Built a scalable embedding-based retrieval system with a large multimodal language model component, increasing design success rate by 9.13%, seen rate by 3.78%, and kept rate by 16.83%.
- **Invitations, banners, posters:** Designed and iterated on LLM prompting architecture and evaluation pipeline for diffusion-based artifact creation, including text replacement with localization capabilities.
- Automatic LLM prompt optimization: Applied internal prompt optimization tool to several Designer artifacts, creating new LLM prompting layers, facilitating prompt iteration and model upgrades, and achieving 76.47% improvement over baseline for invitations artifact and reducing problematic generations by 47%.
- Visual creation in M365 Copilot Chat: Led integration of visual creation capabilities into M365 Copilot Chat and Microsoft Visual Creator Copilot extension with **5K DAU**.
- Infographics prompting: Created icon swap flow and reduced prompt length from 7.245 tokens to 388 tokens and error rate from 4.18% to 0%. Evaluated prompt on 85 languages, ensuring broad coverage.

Education -

Carnegie Mellon University School of Computer Science

Pittsburgh, PA August 2022

Master of Language Technologies

Supported by NSF Graduate Research Fellowship

QPA: 3.80/4.00

Advisor: Yonatan Bisk

Carnegie Mellon University School of Computer Science

Pittsburgh, PA May 2020

Bachelor of Science in Computer Science, Minor in Machine Learning

QPA: 3.95/4.00 Dean's List: Fall 2016 - Spring 2019 College & University Honors

Senior thesis: *Investigating and Robustifying Proximal Policy Optimization* Advised by Emilio Parisotto, Adarsh Prasad, and Ruslan Salakhutdinov

Research Projects –

Learning Visual Representations through Embodied Interaction Exploration

August 2020 - July 2022

- Created Find One and Interaction Exploration environments in Python built on AI2THOR interactive embodied household robotics simulator to explore visual representation learning with embodiment
- Designed customizable ResNet visual encoders and decoders and LSTM policy model architectures in **Pytorch** for control with pixel inputs and outputs and designed a self-supervised policy and visual pretraining task
- Implemented custom variants of reinforcement learning algorithms Advantage Actor-Critic and Proximal Policy Optimization with hogwild asynchronous multiprocess training to allow running 8+ parallel environments
- Built multiprocess autoencoder baseline, supervised topline, and visual probe experiment pipeline to evaluate quality of learned representations on datasets with 2M+ images generated from different heuristic agent policies in AI2THOR simulator

On Proximal Policy Optimization's Heavy-tailed Gradients

August 2019 - May 2020

Accepted to ICML 2021

<u>Proprioceptive Spatial Representations for Generalized Locomotion</u>

June 2018 - July 2019

Accepted to Workshop on Structure & Priors in Reinforcement Learning at ICLR 2019

Skills —

Languages: Python ~ C# ~ C/C++

Technologies: LLM prompting ~ Pytorch ~ Tensorflow/Keras ~ OpenCV ~ Numpy ~ Pandas ~ Docker ~ Git

Last updated May 17, 2025